

Efforts Toward Development Of A High Resolution Global Climatology Of Overshooting Cloud Top Detections Using MODIS and Geostationary Satellite Imager Data

Kristopher Bedka and Patrick Minnis

Science Directorate, NASA Langley Research Center

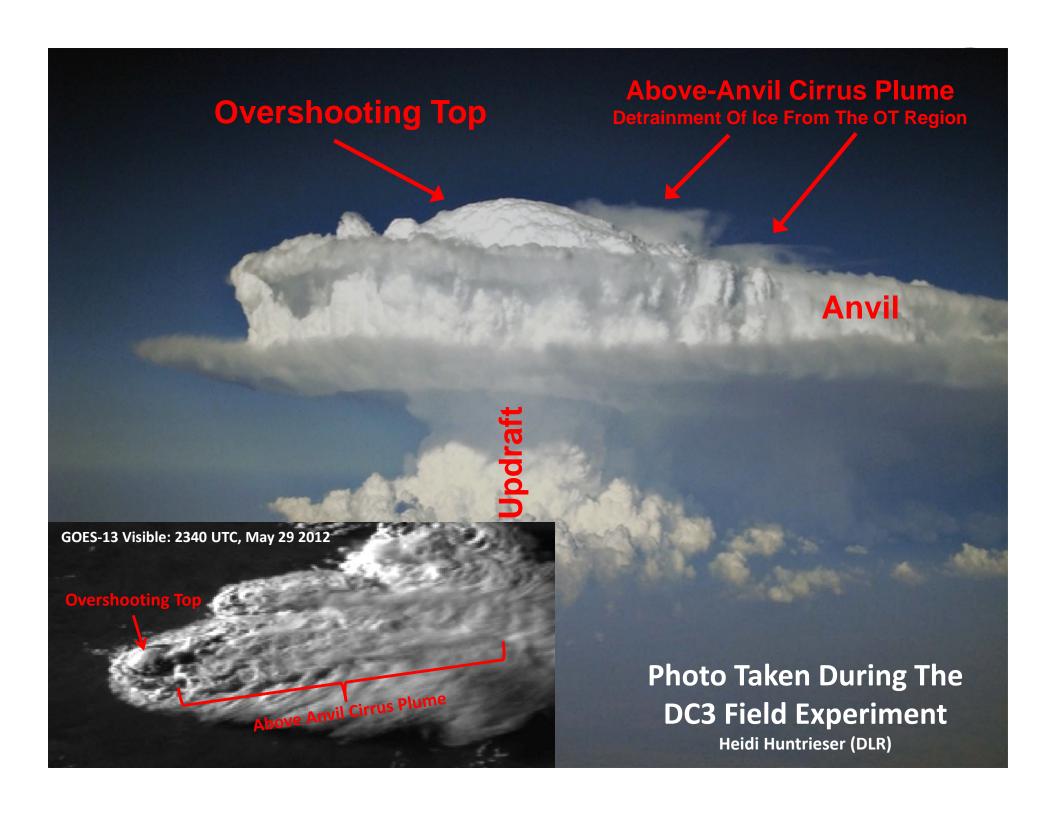
Konstantin Khlopenkov

Science Systems and Applications, Inc

State-Of-The-Art Overshooting Cloud Top Analyses (circa 1972)

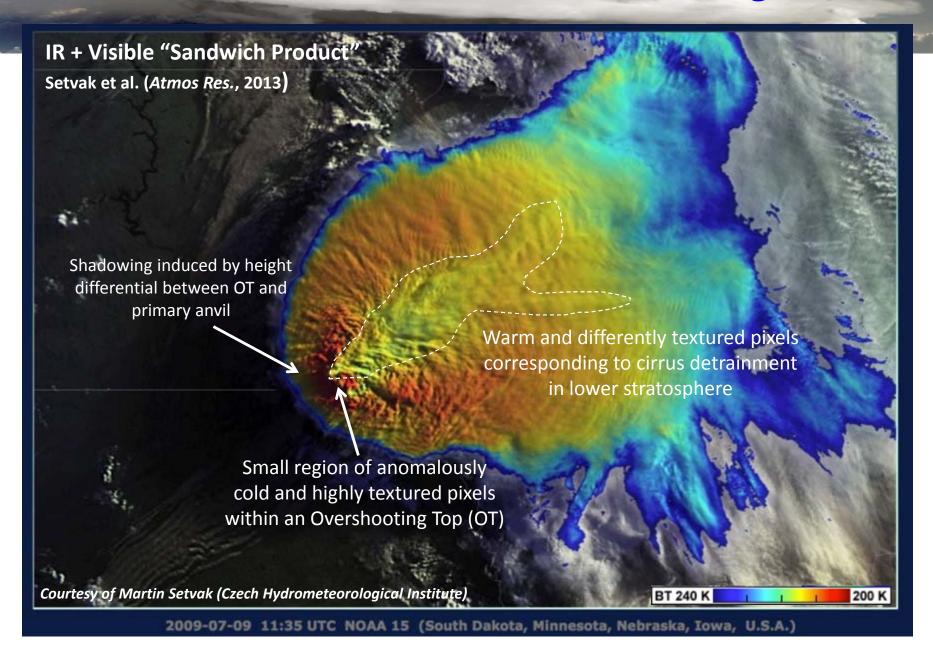
ATS-1 satellite imagery with hand contoured radar echoes taped to a monitor, 13 July 1972





What Do I Consider To Be An Overshooting Top?



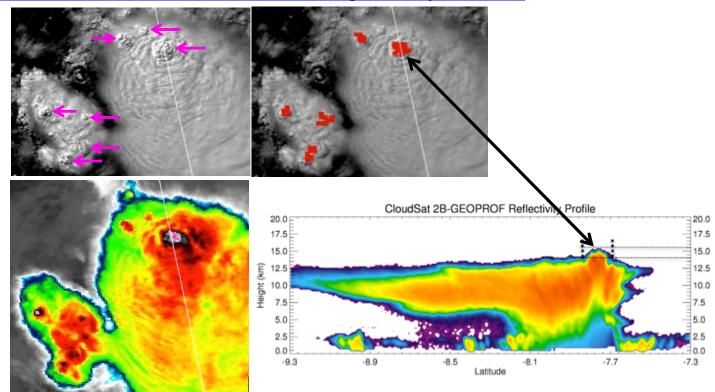


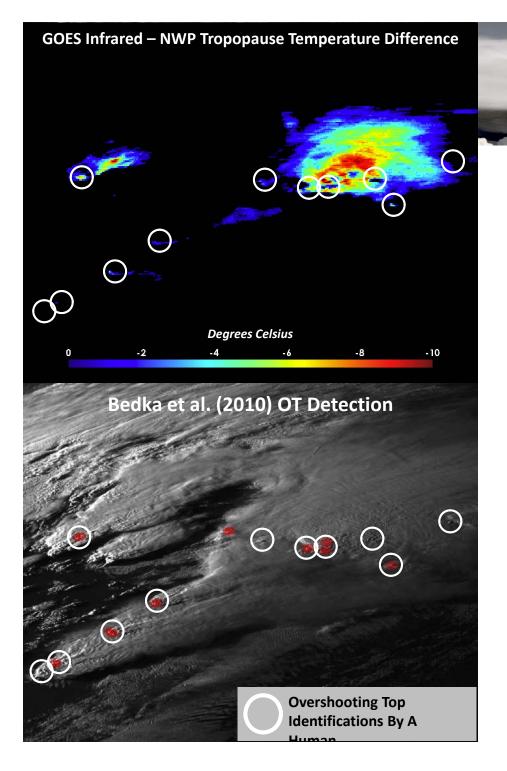
Bedka et al. (2010) IR-Based Overshooting Cloud Top Detection

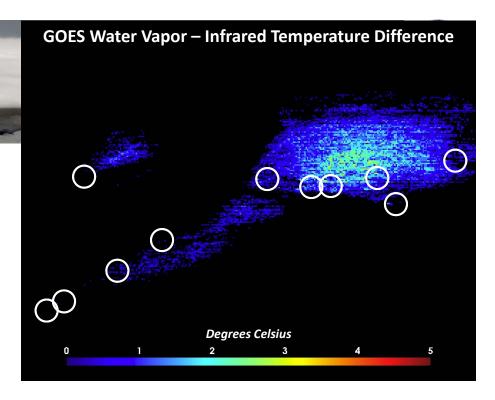


- Hazardous and UTLS-penetrating convective storms typically have one or more overshooting top (OT) regions
- A satellite-based OT detection method was funded by the NASA Applied Sciences Program and GOES-R ABI Aviation Algorithm Working Group for near real-time aviation safety and weather forecast applications (Bedka et al. 2010-2012)
- The method uses spatial analysis and thresholding of satellite IR temperature combined with NWP tropopause tempature to automatically identify individual OT regions

MODIS 250 m Visible, 1 km IR, and Overshooting Cloud Top Detections







Limitations of Current OT Detection Approaches

- All approaches use fixed criteria for binary yes/no OT detection
- Detection techniques that use WV signals identify large portions of the convective anvil and are incapable of isolating only OT regions
- Bedka et al (2010) is the only approach that uses spatial analysis of the anvil cloud for detection
- No approches use the visible channel which typically provides the clearest indication of an OT based on texture and shadowing

Probabilistic Overshooting Cloud Top Detection

GOAL: Mimic the human OT identification process using IR & visible satellite imagery and numerical weather analysis model data within an automated computer algorithm

Satellite IR and Visible OT Indicators Derived Via Image Pattern Recognition + NWP Level of Neutral Buoyancy and Tropopause Temperature Fields



Large Training Database of Satellite + NWP Fields For Both OT and Non-OT Anvil Regions



Logistic Regression Model Used To Discriminate Between The OT and Non-OT Anvil Populations



OT Probability Product

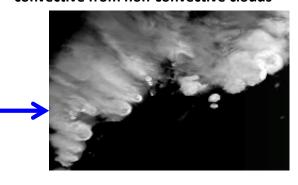
IR-Based Pattern Recognition Analysis

NASA

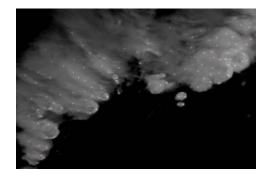
Input MODIS IR
Temperature (BT) Image,
Resampled To 4 km/Pixel
6 May 2007, 1925 UTC

BT Score: BTscore = $(T_{avg} - T)^{0.7} (255 - T)^{1.3} / 1600 + 2 \cdot \sigma(T)$

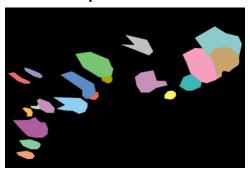
Used to eliminate need for a fixed BT threshold, enhance deep convection, and separate likely convective from non-convective clouds



Identify Local BT Score Maxima
As Initial OT Candidates



Perform Spatial Analysis
Of The BT Score Field
Around Initial OT Candidates
To Map Convective Anvils



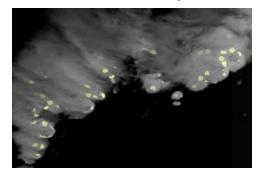
Pattern recognition used to ensure that the region being analyed is within deep convection and 2) the feature of interest has a shape and prominence typical of OT regions

Pattern recognition uses

- OT shape correlation
- BT Score prominence relative to surrounding anvil
- Anvil flatness, roundness, and edge sharpness

The net result is a cumulative rating obtained for each possible OT region. Pixels with a non-zero rating are considered final "OT Candidate" regions

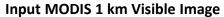
Final OT Candidate Regions
Based on IR Analysis

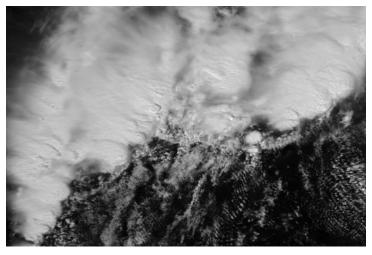


Visible Channel Analysis

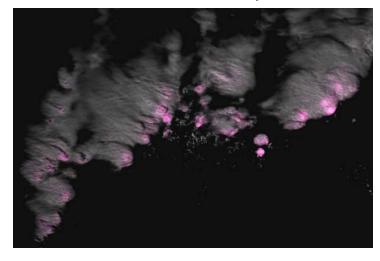


Use a combination of statistical, spectral, and spatial analyses to quantify the degree of "texture" and shadowing present in a visible image associated with OT regions and gravity waves

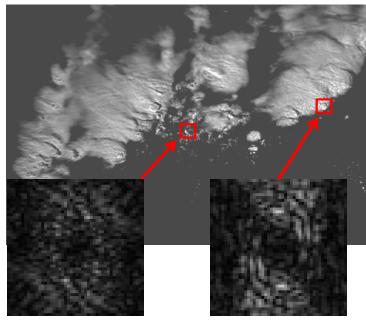




Final OT Candidate Regions Based on Visible Analysis



Statistical and Spectral Analysis To Identify Convective Anvils, OTs, and Nearby Gravity Waves



Fourier frequency spectrum of an area with random spatial variability.

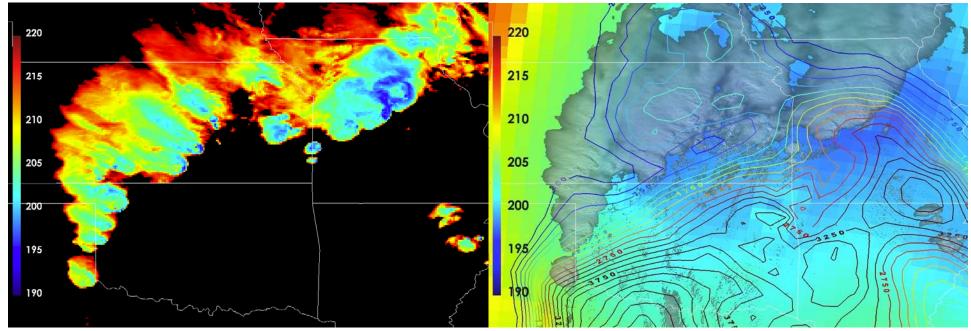
No ring pattern in the spectrum

Fourier frequency spectrum of a typical OT region

Ring fragments in the spectrum can be identified

Input MODIS Infrared Image

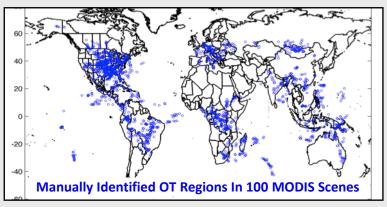
MODIS Visible Overlaid With NWP Tropopause Temp and CAPE Contours



- A set of NWP-based parameters were evaluated for statistical significance in a logistic regression model
- The 1) Satellite Infrared Tropopause Temperature and 2) Infrared Most Unstable Level of Neutral Buoyancy Temperature difference fields were significant for OT discrimination at the 99+% confidence level

Logistic Regression and Final OT Detection Produce

A database of ~2000 OT events were manually identified in 100 daytime Aqua MODIS 250 m visible images. A similar number of non-OT anvil regions were also identified. This database is used to train and validate a logistic regression model to assign high detection probability to OT-like features

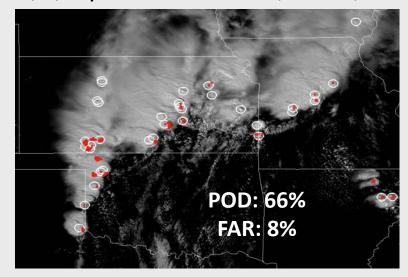


Regression Result = $W_0 + W_1^*(OT\text{-Mean Anvil IR BT}) + W_2^*(IR BT - Tropopause Temp) + W_3^*(IR BT - MU LNB Temp)$

OT Probability

1
-----(1+exp(-1*Regression Result))

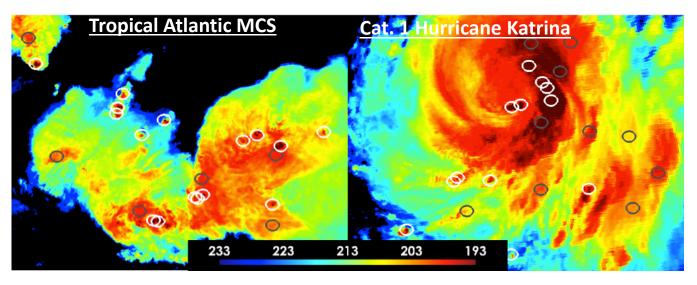
OT Probability ≥ 0.5 (Red) Atop Human-Identified OTs (White Circles) and 250 m Visible Imagery



NASA

OT Detection Validation

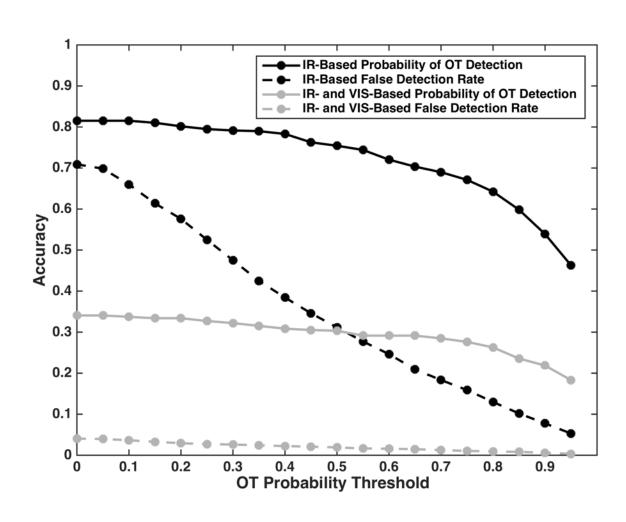
How Well Can The Algorithm Discriminate Between Human-Identified OT Regions (White Circles) and Non-OT Regions (Grey Circles)?

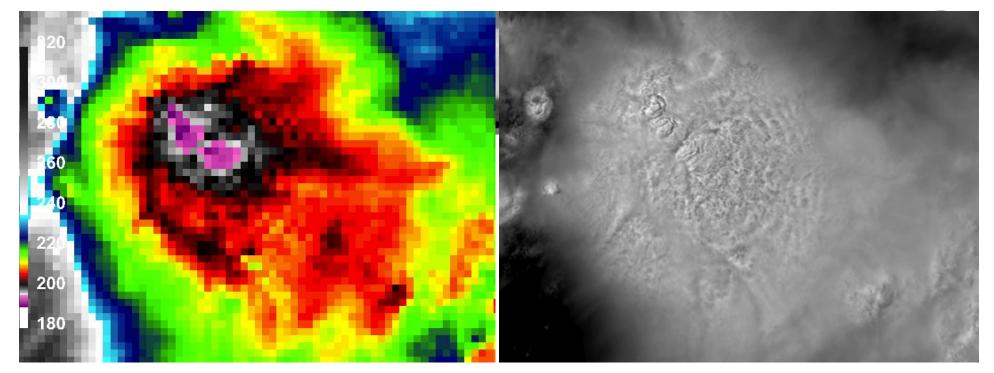


Number of OT Regions 809	Number of Non-OT Regions 615
Number of OT Regions With OT Probability ≥ 0.5 593 (41.6%)	Number of Non-OT Regions With OT Probability ≥ 0.5 58 (4.1%)
Number OT Regions With OT Probability < 0.5 or Lack of OT Detection 216 (15.2%)	Number of Non-OT Regions With OT Probability < 0.5 or Lack of OT Detection 423 (39.1%)
OT Discrimination Skill: 80.7%	



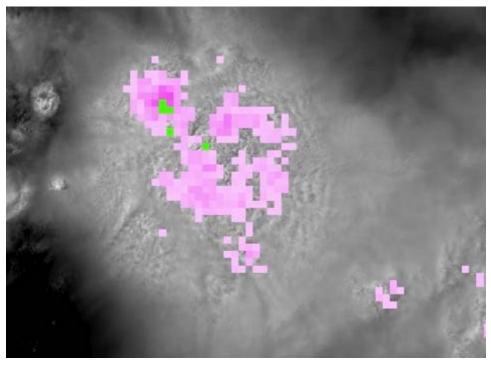
OT Detection Validation

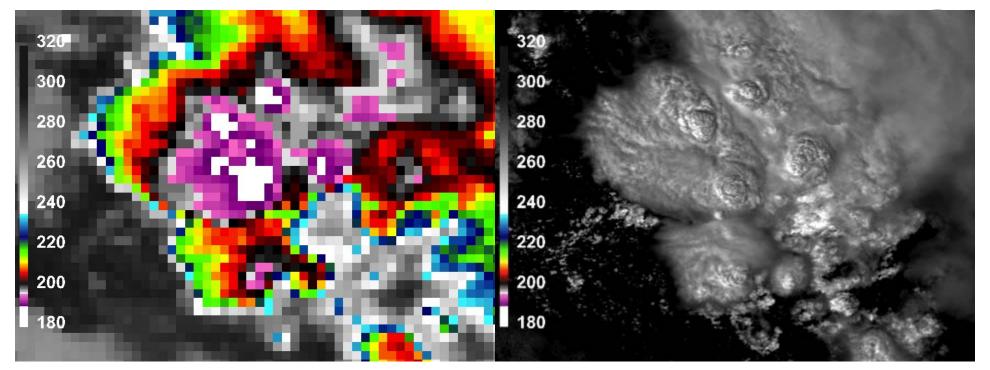




MODIS Tropical OT Detection Example

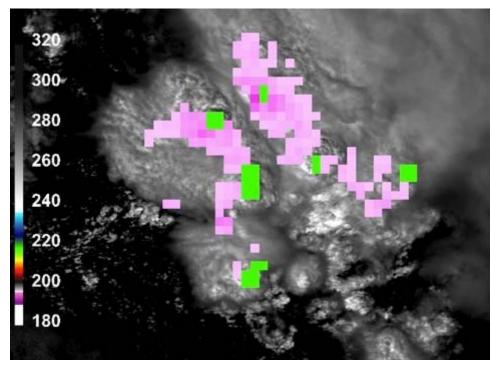
Central Atlantic Ocean
5 August 2008, 1555 UTC





MODIS Tropical OT Detection Example

Eastern Congo 29 November 2008, 1215 UTC

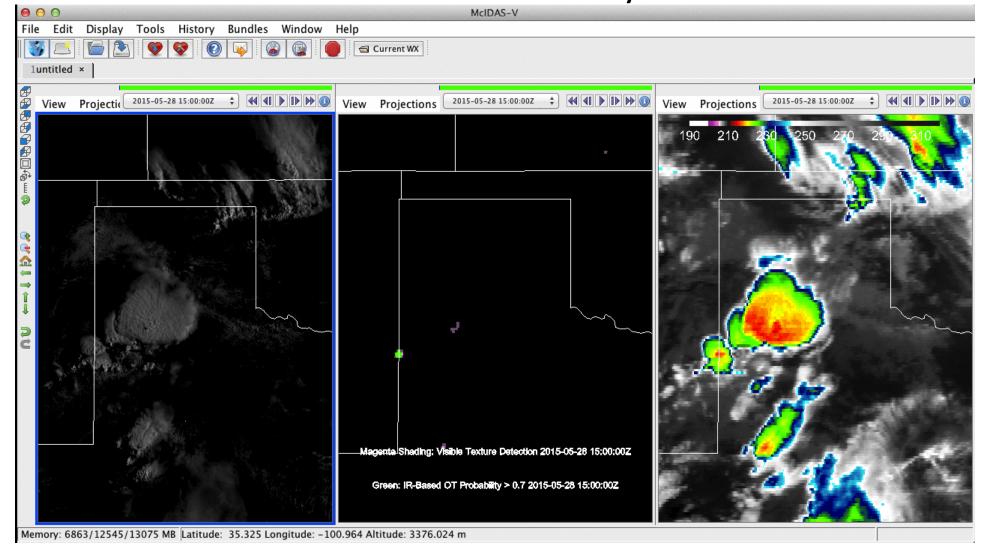


GOES-14 1-Min Imagery



Severe Storms Over the TX Panhandle: May 28 2015

Magenta: Visible Texture Detection Green: IR-Based OT Probability > 0.7



UTLS-Penetrating Storm Database over the African Great Lakes Region



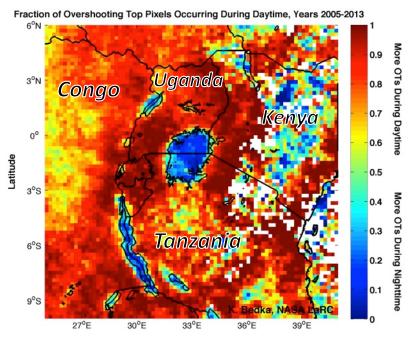
Lethal weather on 'world's most dangerous lake' **CM** World

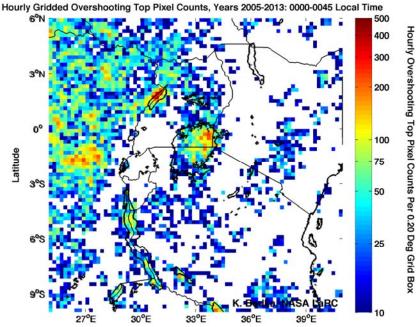
From Errol Barnett, CNN updated 9:48 AM EST, Thu January 17, 2013

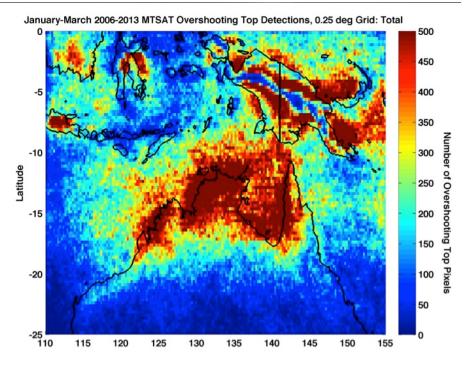


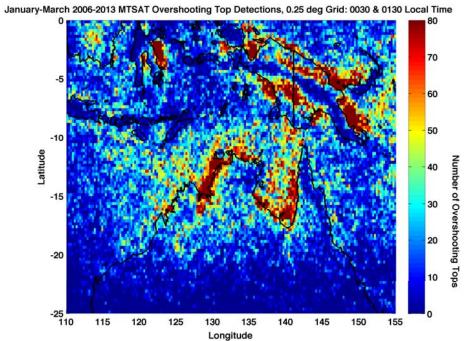
5000+ people are killed on the African Great Lakes every year, most often caused by severe weather

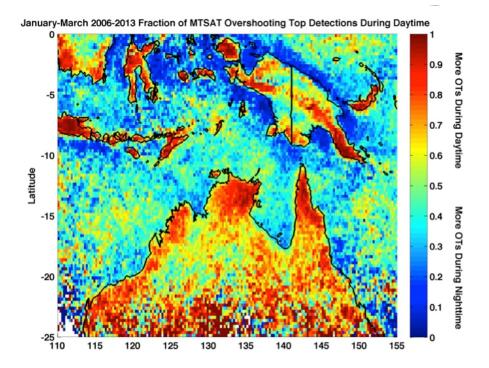
NASA LaRC and international partners are trying to determine the controlling factors for the occurrence of hazardous thunderstorms over the African Great Lakes region via a regional climate model and satellite-based OT detection





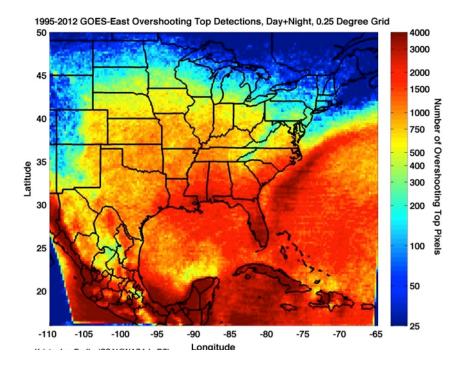






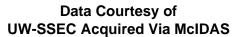
UTLS-Penetrating Storm Database over the Maritime Continent and Australia

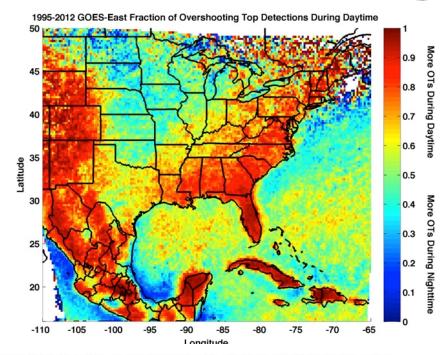
- Generated using hourly data from MTSAT,
 January-March 2006-2013 in preparation for the international HIWC/HAIC field campaign
- Illustrates interesting diurnal variability in storm frequency and distribution

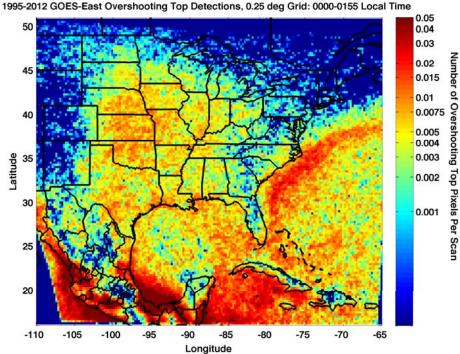


1995-2012 GOES-East OT Detections Using ~4 km Spatial Resolution Data and Two Images Per Hour

OT Detections Assigned To A 0.25 Degree
Resolution Grid

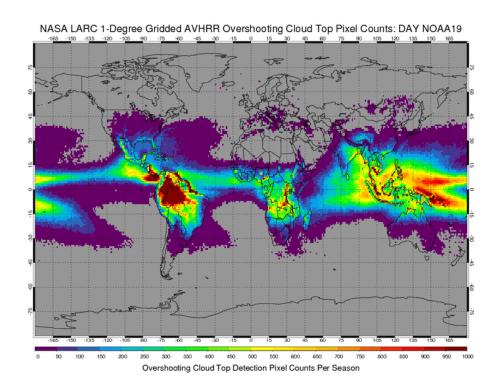


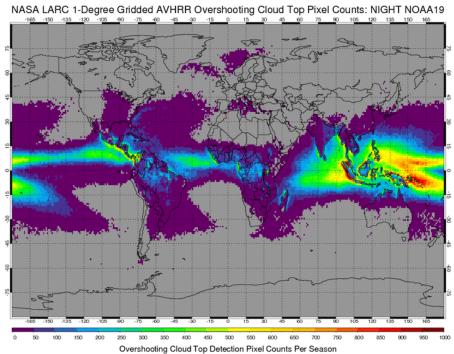




20+ Year AVHRR OT Detection Database



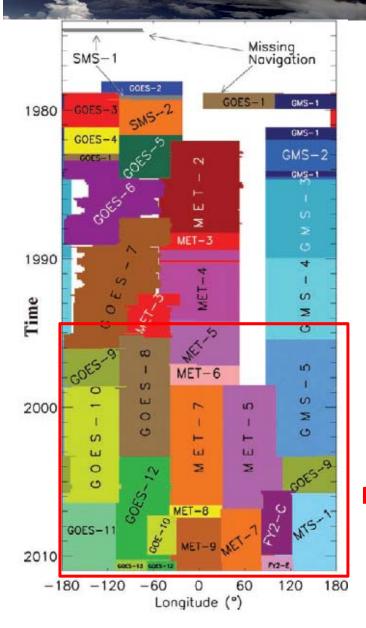




Global GEO Satellite Imager History From Knapp et al. (BAMS, 2011)

Toward A Global Climatology of Overshooting Cloud Top Events

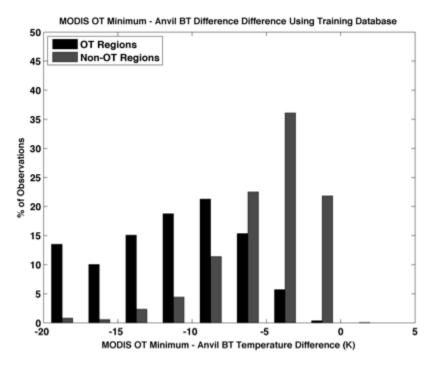


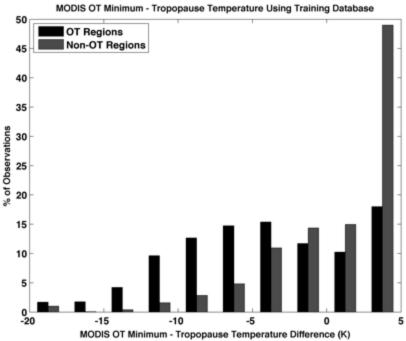


- The global constellation of geostationary (GEO) imagers have been collecting high spatial resolution (< 5 km) IR imagery since the mid-1990's
- NASA LaRC has immediate access to the entire GEO image data archive via McIDAS. User requested data is available within < 30 seconds of request, enabling rapid development of a near-global satellite-based UTLSpenetrating storm dataset
 - Remaining challenges include:1) GEO intercalibration
 - 2) Viewing angle induced biases on IR brightness temperature
- ≤ 5 km IR Spatial Resolution
- Challenges can be addressed by anchoring calibration to stable, long-lived LEO satellite imagers, i.e. MODIS, AVHRR, or HIRS and building LEO-GEO viewing angle dependency models

Summary

- An automated overshooting cloud top (OT) detection algorithm has been recently improved in support of the GOES-R Advanced Baseline Imager program
- The algorithm uses advanced statistical, spatial, and spectral analyses to identify OT signatures at the individual satellite imager (~5 km) pixel scale
- An automated OT detection product has been demonstrated or could be used in a number of applications:
 - 1) Development of a hail risk model for the reinsurance industry (Punge et al. 2014)
 - 2) Analysis of storm distribution throughout the diurnal cycle over the African Great Lakes region (Thiery et al. 2015)
 - 3) Hazardous storm nowcasting by NOAA and within airborne field campaigns (e.g. High Ice Water Content High Altitude Ice Crystals (HIWC-HAIC), GRIP, and HS3)
 - 4) Analysis of the origin of stratospheric WV plumes during SEAC4RS
 - 5) Validation of weather or climate model predictions of UTLS-penetrating storms
- The highly efficient nature of the algorithm coupled with immediate access to the entire geostationary image archive from NASA LaRC enables development of a 20+ year OT event climate data record that can be used by the community to derive trends in global UTLS-penetrating storm frequency and distribution







Histograms of OT and Non-OT Regions

